

Speed Dome Manual v2.1

Precaution

1. Precaution

Electrical safety

Conform to country and local electrical safety standard when using or installing the product.
Using local special power adapter.

Transportation

The dome should be protected against extremes of pressure, vibration and humidity during storage and transportation. It should be shipped in parts disassembled as the original packing did. Damage caused by improper transportation is not within the warranty.

Installation with care

Do not install it in any other orientation. Do not squeeze or structure parts, which may cause mechanical damage. Dome cover is a precise optical product. Do not touch it directly to avoid scratches which can affect image quality.

Requirements to service personnel

All the service work should be done by qualified technicians.

Environmental requirements

Operation environment temperature: -10°C ~ +60°C (40~+30°C (solid disk heater))
Humidity: < 90%
Air pressure: 86~106Kpa

Don't place the camera to be shoot by strong light objects

Don't place the camera to be shoot by strong light objects. Don't point the dome to the sun or other bright objects when in use or not. It may affect image quality.

2.2 Product schematic drawing

1. Connect the power line, video cable and RS485 cable.

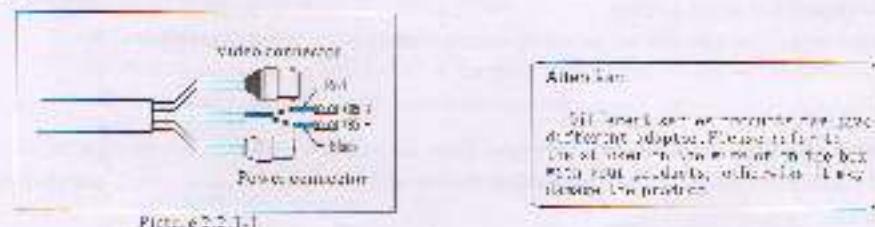


FIGURE 2.2.1-1

3 Performance and feature

This product is high technology surveillance product with high definition and color camera, variable-speed pan/tilt and multi-function decoder. It can reduce the connection and installation process between systematic parts at a time limit, and also can improve the stability and reliability of the system. Meanwhile it is easy to install and repair, and it has the following advantages: beautiful shape, rotate lightly and neatly, little noise, simple operation and so on.

1. Built-in digital camera

- High sensitivity, high resolution, and integrated digital processing
- Auto-focus
- Auto brightness control
- IR cut filter
- Auto-white balance
- Auto-back light compensation
- Auto slow shutter

2. Integrated and multi-protocol decoder

- Unique design, all the data are stored in the inner of camera pan/tilt, when power off, the storage data can't be lost.
- Built-in decoder, integrated multi protocol, including PELCO-D, PELCO-P, FACTORY, etc.
- 128 presets can be stored, preset 1~80 support auto tour, and each tour can store up to 32 presets.
- 4 motions, 4 scenes, 4 tours
- Built-in direction indicator and temperature indicator
- RS485 bus controlling in series, and dodec ID 1-255 optional

3. Built-in pan/tilt

- Iron and carbon alloy structure, high intensity, and good heat dissipation.
- Precise stepping motor, rotate smoothly, react sensitivity and orientate accurately.
- Exquisite mechanical drive, support pan 360° continuously and tilt 0~90°, and may rotate 180° with auto flip.
- Rotate slowly at about 1°/s, and the image doesn't jitter.

4. OSD menu

- All the menu option are displayed in English.
- Video OSD menu. It is direct and simple to revise the camera information and parameter by keyboard and menu display.
- May set park action, and set power up action or carry out appointed action.

5. Internal temperature test

- When the temperature exceeds the upper limit, the screen will display a warning message.
- According to the real-time temperature, the fan will measure if it's static or not, and prolong the life of fan.

4. Function instruction

This passage mainly describes the main function and general principle of mini-speed dome, and does not refer to the operation methods.

4.1 Auto-run motion

● Focus/speed proportion pan

When initially adjusting, for far focus situation, the dome responds at a high-speed so that turning rocker slightly may make picture move rapidly, thus cause the picture to lose. To base on humanized design, the dome automatically edits parameter all rotation according to zoom near and far, which make it convenient to operate manually to track for the object. In the menu, you may change system parameter setting proportion pan as ON, thus you may use this function.

● Auto flip

If user holds the joystick in the down position, the camera rotates pan 180 degrees, then the camera rotates tilt up to 90 degrees, you may directly watch the rear view to realize surveillance till processes in front 180 degrees. In the menu, you may set the system parameter setting AUTO FLIP as ON, thus you may run this function.

● IDLE RUN

By the menu "IDLE RUN" (the "idle action"), user may set auto-call preset or run tour, pattern, and scan, etc after pointing a few minutes if the dome doesn't run any motions.

● Power up run

By the menu "power up run", after the dome powers up or restarts, user may set auto-recording, lens belief power up and auto-call preset or run tour, pattern, and scan etc.

4.2 Camera control

● Magnification control

The user can control 'Wide/Tele' to adjust zoom & field of the image by keyboard controller to obtain panoramic image or close view that you need. Fast speed dome support digital zoom and optical zoom.

● Focus control

System defaults Auto focus. When the lens changes, camera will turn-adjust focus according to the centre of the image to get legible image; user also can manually focus to get desire image by operating keyboard 'FAR/NEAR'. When operating keyboard joystick, camera resumes to auto-focus.

The camera cannot auto-focus in the following status:

- Target is not the centre of the image
- Observation the target near and far at the same time, or a net too close at the same time.
- Target is a strong light object, such as spotlight etc.
- Target moves too fast
- Target is subject, such as wall
- Target is too dark to value
- Target image is too small

O Iris control

System defaults Auto Iris. Camera can rapidly adjust size of iris, through the automatically induct far changing of scene environment, and thus make the brightness of different image variable.

User may adjust iris by controlling keyboard "OPEN/CLOSE" to get required brightness that you need. User also can resume auto Iris by joystick operation. When controlling the Iris manually, the dome looks current position you manually controlled; when operating joystick, the dome resume auto Iris.

O Auto back light compensation

Camera sub-system can carry out auto back light compensation. Under a strong light background, camera will auto compensate light for the darker object and adjust daylight to the bright background. In order to avoid making the image lack fidelity the back light is too bright, and the object is unable to recognize because of darkness, thus get illegible image.

O Auto white balance

Camera can automatically adjust white balance in accordance with the alteration of background's lightness to reach a true color.

4.3 Monitor function**O Set and call preset**

Preset function is that dome stores current pan/tilt, angle, zoom and other position parameters into the memory. When necessary dome recalls these parameters and adjust camera to that position. User can store and recall presets easily and promptly by using keyboard controlling. The dome can store up to 128 presets.

O Tour

Tour is the built-in function in the speed dome. It can appoint setting in advance, and make presets arranged in needful order in tour dwell. By inserting preset in tour dwell, to make the camera tour between these preset. Tour order can be programmed, each time you run tour, you don't set park times. A tour can store 22 preset.

O Scan

User can easily preset right limit and left limit by controlling menu and menu, in order to make the camera scanned between right limit and left limit at a setting speed.

O Pattern

Pattern is built-in function in the speed dome: the dome can record 16 tracks that are no less than 180°, when running pattern, the dome moves repeatedly according to the recorded tracks. Each dome can set up to 4 pattern.

O Lens position display

The position that the speed dome has finished to self-focusing, as it point of pan rotation and tilt rotation. The pan range is 0-360°, and tilt range is 0-90°. According to the displayed information, to set the position of camera lens, and the position can display on the screen.

4.4 Constant temperature Function

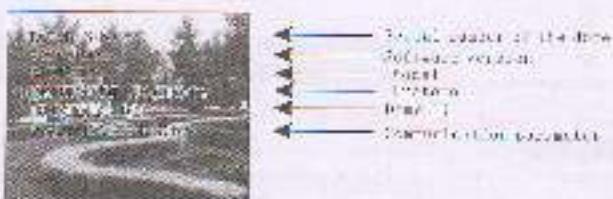
Infrared temperature sensor surveillance temperature inside of the dome. When the dome work in the high temperature, the dome will automatically turn up the fan to reduce the heat, to make sure the dome work in the reliable temperature environment, increases its stability and prolong the life time of the dome.

5. System setting

5.1 Basic operation

5.1.1 Power up and self-testing

The dome conducts self-testing after current starting, and it rotates slowly until displaying the origin that is default setting, then moving to tilt center; when self-testing is finished, there is relevant system information displaying on the screen, as follows:



The information will not disappear until you stop to operate the system in 10 seconds, "power up action", the dome will automatically return to its initial position after self-testing. How to operate the function? We will explain in detail in the following passages.

5.1.2 Call the main menu

The system enters into the main menu by 95 preset or two times left 9 preset in 2 seconds. All the menu setting must enter into the main menu at first.

5.1.3 Menu and keyboard operation

① Keyboard operation:

【OPEN】: when choosing menu, it means to enter the next menu or enter into setting, or save after finish to set.

【CLOSE】: when choosing menu, it means to close to cancel, or exit to the former menu.

Joystick to up: When choosing menu, it means to choose the former one; when choosing picture, it means camera tilt up.

Joystick to down: when choosing menu, it means to choose the next one; when choosing picture, it means camera tilt down.

Joystick to left: when choosing menu, it is equal with 【Close】; when choosing picture, it means camera tilt left.

Joystick to right: when choosing menu, it is equal with 【Open】; when choosing picture, it means camera tilt right.

Press 【TRI.F】 and 【WIDE】 at the same time, it means 3D joystick makes joystick stop.

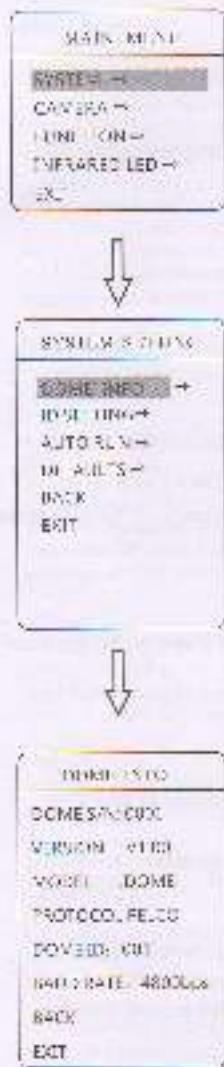
② Menu operation:

"BACK": Back to the former menu.

"EXIT": Exit to menu.

"ON": Open some setting.

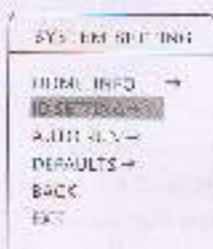
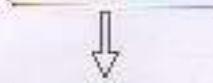
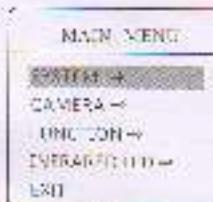
"OFF": Close some setting.



5.3 Dome initial information

1. Call 95 preset or trackball 9 preset twice in three seconds to enter the main menu.
2. Operate the joystick up and down and move the cursor to [SYSTEM] , press [OPEN] to enter submenu.
3. Operate the joystick up and down and move the cursor to [DOMEINFO] , press [OPEN] to display initial information as the left picture shows.

Initial information includes S/N of the dome, software version, product, dome ID, communication parameter. SYSTEM may change the numerical value of initial information.



5.4 ID Setting

1. Call 95 preset, or call 9 preset twice within 3 seconds, to enter into main menu.

2. Operate the joystick up and down and move the cursor to [SYST-EM 1], press [OPEN] to enter submenu.

3. Operate the joystick up and down and move the cursor to [ID SETTING], press [OPEN] to call dome parameter setting menu.

【S/N】 : Series number of the dome

【CONF】 : Confirm S-N and input the same number with S/N

【ID】 : Set dome address (ID range: 00 ~ 255)

The shortcut of Dome ID setting: call 01-116 preset twice within 3 seconds, to set dome ID as 1 to 16, for example, call 103 preset twice within 3 seconds, then dome ID be setted as 3.

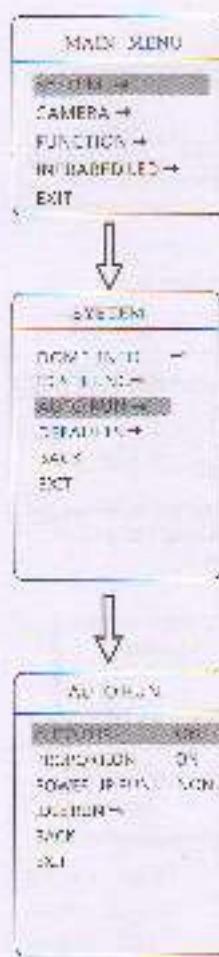


NOTICE

1. If [S/N] and [CONF] are not 110, the above operation can't be implemented.

2. The dome address should be static 255 by setting SW1 as DYN=1. And, there will be display this item [DOME ID].

3. After setting dome address, the dome need to restart, then the dome address will be effective.



5.5 AUTO RUN

Systematic motion controlling way control a series of continuous movement of the dome, and plays an important role in controlling the image of the dome.

1. The system enters into the main menu by calling 95 preset or by calling 9 preset, twice with 0.3 seconds.

2. Operate the joystick up and down and move the cursor to [SYNTHESIZE], press [OPEN] to enter and choose [AUTO RUN].

5.5.1 AUTO FLIP

Operate the joystick up and down and move the cursor to [AUTO RUN], press [OPEN] to enter and choose [AUTO RUN]. Operate the joystick up and down to choose ON to open "auto flip", and choose OFF to close "auto flip". Press [OPEN] to save.

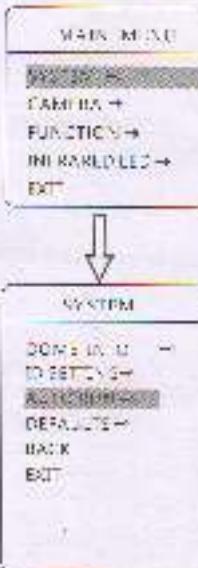
[OPERATION KNACKS]

When manually operating, for focus function, the dome responds very sensitively but touching rocker slightly may make pictures unclear, thus cause the motion unclear. To have an humanized design, the dome automatically rotates just one direction returning from one end to another, which makes it convenient to operate manually, and after object.

5.5.2 PROPORTION

Operate joystick and move the cursor to [PROPORTION], press [OPEN] to enter "proportion" setting, operate joystick up and down to choose, if choosing [ON], it means to open proportion pan. If choosing [OFF], it means to close proportion pan, press [OPEN] to save.

SYSTEM



5.5.3 Power up run

The device startup to run actions after self-testing, if nobody intervenes with it, the device will repeatedly run this action continuously, if default sets to [NONE].

Operate joystick, move the cursor to [POWER UP ACTION], press [OPEN] to jump to the following choice, tilt up/down joystick to choose 'power up action', press [OPEN] to save.

- [NONE] : none action
- [AUTO] : the device resumes the primary action and direction before power up:
 - [PRESET] : use preset
 - [SCAN] : run scan
 - [PAT] : run pattern
 - [TOUR] : run tour

5.5.4 IDLE RUN

This setting allows the device to run an appointed action after it enters vacancy for a few time (1-240 minutes). If default sets as 0, it means not to run this action.

1. Operate the joystick up and down and move the cursor to [IDLE RUN], press [OPEN] to tilt up/down joystick to set idle time, the range is 0-240 (minutes), press [OPEN] to save. [PARK ACTION] is running action at park time, when [PARK TIME] sets as 0, this item can't be set.

2. Operate the joystick up and down and move the cursor to [IDLE ACTION], press [OPEN], here will be a sign "OR" in the front of [IDLE ACTION], the cursor jump to right, after tilting up/down joystick to choose 'idle action', there are opt. ons for choosing as follows, press [OPEN] to save.

- [NONE] : (default) no action
- [PAT] : run pattern
- [TOUR] : run tour
- [SCAN] : run scan
- [PRESET] : use preset



5.6 Defaults

1. The system enters into the main menu by calling 95 preset or by calling 9 preset twice within 3 seconds.
2. Operate the joystick up and down and move the cursor to [SYSTEM], press [OPEN] to enter submenu.
3. Operate the joystick up and down and move the cursor to [CLEAR ALL PRESETS], press [OPEN] to enter submenu, as left picture shows
 - [CLEAR ALL PRESETS]
 - [CLEAR ALL PATTERNS]
 - [CLEAR ALL TOURS]
 - [FACTORY DEFAULTS] - assume the factory default.
 Run this function, the camera parameter and system parameter will resume before production, clear all windows and alarm setting. Please be cautious to use this function.
 - [RESTART] - restart the device



Once select all commands in the configuration menu,
they don't resume, so please be careful of using



6. Function setting

6.1 Preset

1. The system enters into the main menu by setting 95 preset or by calling 'Preset' twice within 3 seconds. Click each command to enter 'preset menu' according to the order of the left picture. As follows:

- [PRESET NUMBER]
- [SET PRESET]
- [SHOW PRESET]
- [CLEAR CURRENT PRESET]

Define preset and call preset function can be set by keyboard operators, input preset number at first, then click the key "store all preset" to carry out.

2. Define current preset number: move the cursor to [PRESET NUMBER], press [OPEN] to choose preset number, the range is 01 - 128 as the left picture shows, here defines number 5 as current preset, the following operations aim at the current preset.

3. Define current preset: move the cursor to [SET PRESET], press [OPEN], by operating joystick to adjust magnification, to choose good objective image, press [OPEN] to save. If the image is very dim, the image is below a digital zoom, when setting preset, the image will prior to maximal optical zoom.

OPERATION TIPS

Preset function, that does not need parallel angle, zoom and other location parameters into the memory. When necessary come really these parameter and return comes to real position.

4. Display current preset: move the cursor to [SHOW PRESET], press [OPEN], the screen will display the current preset.

5. Clear current preset: move the cursor to [CLEAR PRESET], press [OPEN], the current preset is cleared.



6.2 Scan

Scan is that pre-set two points, then the car moves repeatedly scan between the two points at a stable speed, the same magnification and pan, back camera has function.

1. The system enters into the main menu by setting 95 preset or by calling 9 preset twice within 3 seconds. Click menu to enter "scan" menu, as the left picture shows

- [SCAN NUMBER]
- [SCAN SPEED]
- [SET LEFT LIMIT]
- [SET RIGHT LIMIT]
- [RUN SCAN]
- [CLEAR SCAN]

2. Define current scan number: operate joystick, move the cursor to [Scan Number], press [Open], tilt up/down joystick to choose scan number, press [Open] to save. The following operation is all of the current scan number.

3. Scan speed setting: operate joystick to [SCAN SPEED], press [OPEN], tilt up/down joystick to adjust scan speed, press [OPEN] to save.

4. Left limit setting: operate joystick to [SET LEFT LIMIT], press [OPEN], operate joystick to choose objective range, press [OPEN] to save. Right limit setting is the same as left limit setting.

5. Run scan: operate joystick to [RUN SCAN], press [OPEN] to exit the menu, and it starts to run scan.



6.3 Pattern

Pattern is built-in function in camera. The speed dome can record tracks that are no less than 180° (A series of pan/tilt controlling and lens controlling commands). Each dome may set up to 4 patterns.

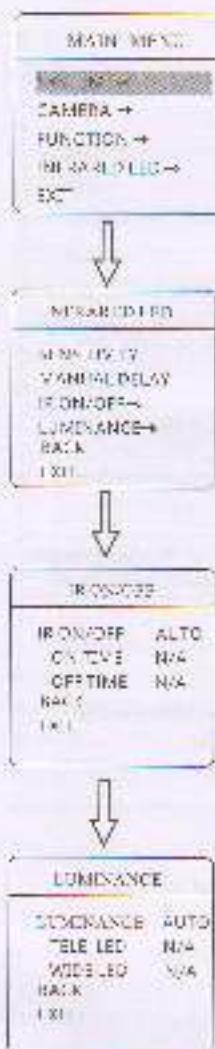
1. The system enters into the main menu by calling 95 preset or by calling 9 preset twice within 3 seconds.
2. Operate the joystick up and down and move the cursor to [FUNCTION SETTING], press [OPEN] to enter submenu.
3. Operate the joystick up and down and move the cursor to [PATTERN], press [OPEN] to enter menu "Pattern".
 - [PATTERN NUMBER]
 - [RECORD PATTERN]
 - [RUN PATTERN]
 - [CLEAR PATTERN]
4. Choose pattern number; move the cursor to [PATTERN NUMBER], press [OPEN], the pattern you choose as current one, the following operations control the current pattern.
5. Define current pattern: move the cursor to [RECORD PATTERN], press [OPEN] to set pattern track, move the image random, and draw the locus. Each dome has a rear that is no less than 180°, a series of work time, magnification, focus will be recorded, press [OPEN] to save.
6. Run pattern: operate joystick to [RUN PATTERN], press [OPEN] to run, the dome will continuously and repeatedly record the specific track.



6.4 Tour

Tour is the built-in function in the space drama, it will arrange the presets into the queue of auto tour, and can set how long it will stay on preset. Operate auto tour is a process of incessantly transfer each preset. One tour can store 32 presets at most.

1. The system enters into the main menu by calling 95 preset or by calling 9 preset twice within 3 seconds.
2. Operate the joystick up and down and move the cursor to **FUNCTION**, press **[OPEN]** enter submenu.
3. Operate the joystick up and down and move the cursor to **TOUR**, press **[OPEN]** to enter menu "tour".
 - **[TOUR NUMBER]**
 - **[EDIT TOUR]**
 - **[RUN TOUR]**
 - **[CLEAR TOUR]**
4. Set tour: move the cursor to **EDIT TOUR**, press **[OPEN]** to enter tour interface. **[POLE-TIME]** set preset speed and time, press **[OPEN]**, the first dwell is activated, tilt up/down joystick to choose preset number, the preset numerical value should be within 1-80 preset, a total can set up to 32 preset. Press **[OPEN]**, the cursor jump to the next dwell, tilt up/down joystick to choose current arrival preset speed, note level of speed, increasingly from level 1 to level 8. Press **[OPEN]**, the cursor jumps to the next dwell, tilt up/down joystick to set current preset duration time, 60 seconds maximum. If set the preset of the second line, move the cursor to the second line, then press **[OPEN]** to continue edit. Press **[OPEN]** to save that setting, press **[CLOSE]** to exit.
5. Run tour: Operate joystick, move the cursor to **[RUN TOUR]**, press **[OPEN]** to exit the menu, it starts to run tour.



c. Infrared led setting

7.1 IR SENSITIVITY:

infrared automatic open sensitivity settings, range 0~100, the user can choose 0~20 the environmental illumination status module is treated automatically open.

7.2 MANUAL DELAY:

infrared light manual opening, delay time, if time > 0, Do not automatically close infrared lamp

7.3 IR ON/OFF:

IR control menu can be divided into 2, AUTO, MANUAL, TIME. If it is available TIME mode, according to the user set time to switch IR, in MANUAL mode, Ctrl the 62 press, command to open the infrared light, open the 63 press, closed lamp

7.4 IR LUMINANCE:

infrared brightness control method is infrared light, can adjust after. Divided into: AUTO, GROUP, MANUAL, three states AUTO mode, infrared automatic brightness matching lens distance, according to the time, lens changes. Infrared high beam and dipped beam headlights will automatically adjust the brightness, reach the intensity of 100% when infrared brightness automatic matching, and can improve the infrared lamp life.

GROUP mode: package mode, two sets of mode, infrared high beam and dipped beam headlights will work. According to the lens distance packet opened at the same time.

MANUAL mode: the manual control mode, infrared brightness from the lens parameters influence. The user can set the high beam and dipped beam brightness, range 0~100

8 Troubleshooting

Trouble	Possible causes	Solution
No vision, no video after power up.	Power supply is damage or power consumption is not enough	Replace
	User identification wrong	Correct
	Engineering line is malfunction	Check and repair
Self-testing and images are normal but the dome is unaccessible	The dome ID setting is incorrect	Refer to ID setting
	Rs485 may carry out away	Check Rs485 connection, confirm the connection is correct, and gear it correctly
	Rs485 is not functioning	Please see appendix [Rs485 Pinout knowledge]
Video image is not steady	Video line is bad connection	Eliminate
	Power consumption is not enough	Replace right power adapter, it is better to put the switch and power adapter next the dome
Video image is not steady and the motor is faulty	Power consumption is not enough	Replace the power
Dome controlling is not smooth	Controlling line is connected wrong, or Rs485 baud too small or the distance of communication is too far	1. Correct 120Ω resistance in the dome part of the cable from the controller 2. Increase distributor

8.1 The cleaning of clear down cover

To obtain constant clear videos, user should clean the down cover periodically.

- Be caution when cleaning, hold the down cover ring only to avoid direct touch to the acrylic down cover. The acid sweat mark of fingerprint will corrode the coating of down cover and scratch on down cover will cause vague image.
- Use soft dry cloth or the substitute to clean the inner and outer surfaces
- For hand contamination, use neutral detergent. Any cleanser for high grade furniture is applicable.

8.2 RS485Bus basic knowledge

Characteristics of RS485 Bus

As specified by RS485 standard, RS485 Bus is of half-duplex standard transmission cables with characteristic impedance as 120Ω. The maximum load capacity is 32 unit load (one master and one slave controller and controller equipment).

Transmission distances of RS485 Bus

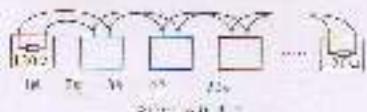
When user selects 16.5mm(21AWG) twin-pair wires as data transmission cable, the max theoretical transmitting distance is as follows:

Band rate	Max distance
≥100bps	1800m
1800bps	1200m
3600bps	800m
19200bps	600m

If user selects thin wire cables, or installs the cable in an environment with strong electromagnetic interference, or connects lots of equipment to the RS485 Bus, the max transmitting distance will be decreased. To increase the maximum transmitting distance, do the contrary.

Connection and termination resistor

The RS485Bus standards require a daisy-chain connection between the equipment. There must be termination resistors with 120Ω (as the picture 9.4-1). Please refer to picture 9.4-2 for simple connection. R_D should not exceed 7m.



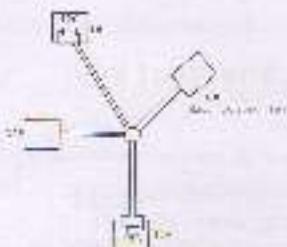
Picture 9.4-1



Picture 9.4-2

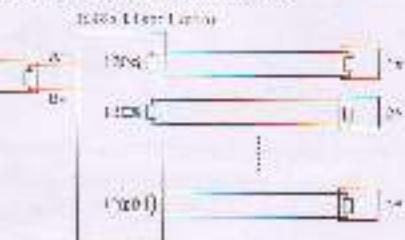
Problems in practical connections

In some circumstances user adopts a star configuration in practical application. The termination resistors must be connected to the two equipment 1# and 12# (picture 9.4-3). As the star configuration is not in conformance with the requirements of RS485 standards, problems such as signal reflections, lower anti-interference performance arise when the cables are too long in the connection. The reliability of control signals is decreased with the phenomena that the slave does not respond at just response at intervals to the controller, or does continuous vibration without stop.



Picture 9.4-3

In such circumstances the factory recommends the usage of RS485 distributor. The distributor can change the star configuration connection to the mode of connection stipulated in the RS485 standards. The new connection achieves reliable data transmission (Refer to Picture 9.4-4)



Picture 9.4-4

RS485 Bus troubles shooting

Trouble	Possible cause	Solution
Device can drive nothing, but can not be controlled	1. The address and bandwidth setting of slave are not in conformity with those of controller. 2. Pin 1 and 2 connection of RS485 bus is incorrect. 3. Pin connection 4. There are short circuit in the RS485 bus.	1. Change the address and bandwidth settings of slave. 2. Adjust the 1 and 2 connection of RS485 bus. 3. Make sure the connections are fully seated. 4. Change RS485 bus wires.
The device can be controlled by the opera- tor panel (HMI)	1. The RS485 bus is not in good contact with the connection. 2. One end of RS485 bus is broken. 3. The device is very far from controller. 4. There are too many slaves connected to the system.	1. Secure the connection. 2. Replace RS485 bus wires. 3. Add termination resistors to the system. 4. Justify RS485 distributor.

9. Shortcut key:

CALL+"N"-PRESET	Show preset
SET "N" PRESET	Save preset
CALL+"95"-PRESET	Enter menu
CALL+"94"-PRESET	Restart
CALL+"92"-PRESET	Set scan Left limit
CALL+"93"-PRESET	Set scan Right limit
CALL+"97"-PRESET	Run scan
CALL+"98"-TRESLT	Run ion1
CALL+"99"-TRESLT	Run scan1
CALL+"62"-PRESET	Open IR LED (manual state)
CALL+"63"-PRESET	Close IR LED (manual state)

9. Maintenance

(1) Range of warranty

- The product will be maintained free for one year.
- The product will be obtained the free maintenance service if the same malfunction appears again within three months.
- Malfunction of products caused by force majeure (such as war, earthquake, lightning strike and so on), abuse, non-standard operation, change of construction, non-normal wear or accident etc not free of warranty.
- Please prevent from the damage which is caused by heavy pressure, the fierce vibration and shocks in the process of transportation and storage, which does not belong to the free maintenance scope.
- Please adopt the way of less package or original package to transport, because the product damage does not belong to the free maintenance scope if you use the whole packing way, not the original packing way.
- The maintenance services will not be free when the panel module is disassembled or serviced by the user voluntarily.
- Our company implements the lifetime payable service if the product in malfunction has surpassed the warranty period.
- To the products with defect, it's in the period of warranty, please fill in the form of warranty information correctly, describe the trouble in details, and provide the trouble in details, and provide original sales invoice or factory.
- For the damage and loss which was caused by the user's specifically application, factory won't bear any risk and responsibility. The factory compensation made by breach of faith, negligence or tortious won't exceed the amount of the products. The factory won't bear any responsibility for the special, unexpected and continue damage caused by any other reasons.
- Our company has the final right of explanation for the above items.

(2) Warranty terms

If the products are within the warranty time, the buyer should fill in the warranty card and send back together with the products.

(3) Shipping

If the product needs repaired, you can return it to the manufacturer through the supplier or directly. If you choose the later, please contact us in order to speed up the process. And our company only undertake the one-way freight from manufacturer to customer after maintenance.